Trusted Firmware - M

Handle Management Mechanism Enhancement

Precondition for fast RoT Services API call

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Content

• Background – To improve the performance of RoT Service API

• Design – Usage analysis and the proposal

• Discussions – Related topics: Memory usage and performance

• Updates since initial version of the proposal
  • Including the service version in the default handle
  • Implementing just-in-time auto-connection within the SPM
Background

• In a Tech Forum so far (Jan 23rd), partners comment that psa_connect()/psa_call()/psa_close() cost much for one-shot service call.

• Here is how we encapsulate a RoT service API today:

```c
int32_t RoTService(void)
{
    handle = psa_connect(SID, VERSION);
    if (!PSA_HANDLE_IS_VALID(handle)) {
        return PSA_HANDLE_TO_ERROR(handle);
    }
    status = psa_call(handle, PSA_IPC_CALL, NULL, 0, NULL, 0);
    psa_close(handle);

    return status;
}
```

• Then some investigation happened to see if we can enhance this part.
Assumptions before going

• Avoid significant changes in PSA FF - Be simple.

• Security consideration
  • Connection-based mechanism is necessary – SPM and services could identify clients by connection.
  • Connecting process is known by services.

• Let’s go through the analysis and possible implementations...
Thoughts – When to call \texttt{psa_connect()}?

- `\texttt{psa_connect()}` is \textbf{always called} while \textit{session-based service API} setup a session.
  - Session-based API has session maintenance process (setup/process/destroy), PSA API can be called during these process.
  - The connecting costs are amortized in the functions that get called.

- One-shot RoT service API is session-less and can \textbf{re-use} the connected handles.
  - From security perspective – SPM and services need to identify clients for access control – connected handles cannot be shared between clients – one client one connection.

```
Open(&ctx);                      \texttt{ctx.h = psa_connect()}
Func1(&ctx);                     \texttt{psa_call(ctx.h, type1)}
Func2(&ctx);                     \texttt{psa_call(ctx.h, type2)}
...                              \texttt{psa_call(ctx.h, typeX)}
Close(&ctx);                     \texttt{psa_close(ctx.h)}
```

```
Oneshot1();
\texttt{psa_call(h, type1)}
Client_Init();
h = \texttt{psa_connect()}
Oneshot2();
\texttt{psa_call(h, type2)}
OneshotX();
\texttt{psa_call(h, typeX)}
Client_Destroy();
\texttt{psa_close(h)}
```

Session-based RoT Service API

Session-less RoT Service API
A Typical Design Candidate – Store the connected handle

• If stored as global variables:
  • RoT Service API is implemented as a library and being shared by multiple clients, how does this library know how many handle variables it should reserve in static allocation case?
  • All Clients share one saved variable – brings more trouble to systems that implement isolation.

• Could resolve this with an abstracted allocation API, but:
  • Involves abstraction layer into library – **More Dependencies!**
  • A system without memory management API?
  • Which handle belong to this caller? – Need an ID to represent the caller.

• **Does not look like a nice solution.**

```c
handle = GET_SAVED_HANDLE(THIS_CALLER_ID);
if (!PSA_HANDLE_IS_VALID(handle)) {
    handle = psa_connect(SID, VERSION);
    if (!PSA_HANDLE_IS_VALID(handle)) {
        return PSA_HANDLE_TO_ERROR(handle);
    }
    SAVE_HANDLE(THIS_CALLER_ID, handle);
}
```
Thoughts – If a service handle is known already?

- No Handle Storing is needed - the client can ‘psa_call()’ on a known handle value:
  - ‘psa_call(SERVICE1_HANDLE, type, ...)’
- Need to make different clients can use the same handle value for the same one-shot service. (An implementation note in PSA-FF-M 3.3.4 now would become a MUST item for one-shot services).

- **Looks like a neat solution.**
Proposal – PSA-FF-M level details

- A new manifest field for services to indicate a default handle **INDEX** for session-less service API usage:

<table>
<thead>
<tr>
<th>'default_handle': &lt;number or pattern&gt;</th>
</tr>
</thead>
<tbody>
<tr>
<td>‘auto’</td>
</tr>
<tr>
<td>System allocation.</td>
</tr>
<tr>
<td>1 ~ DEFAULT_HANDLE_INDEX_MAX</td>
</tr>
<tr>
<td>Expected handle value.</td>
</tr>
<tr>
<td>Field not available</td>
</tr>
<tr>
<td>No default handle value for this service.</td>
</tr>
</tbody>
</table>

- Default handle **VALUE** is decided by the framework/implementation.
  - **INDEX** and service **VERSION** are encoded into **VALUE** using **Implementation-defined** encoding.
  - Two services cannot have the same default handle **INDEX** and **VALUE**.

- Default handle value is assigned to a macro, just like service **SID** and **VERSION**.

- Default handles are connected during the first ‘psa_call()’ with default handle value.
  - Client **explicit** call to ‘psa_connect()’ returns non-default handle value.
  - Closing a default handle causes **PROGRAMMER ERROR** – no closing allowed to avoid affecting other code that is working on this default handle.
Proposal – Implementation ideas: Tooling and Coding

- Tooling to generate the default handle value if ‘default_handle’ detected in manifest
- Rot Service API implementation references the handle by the MACRO.

```

service_a.json:

"name": "SERVICE_A",
"version": 1,
"default_handle": 3

psa_manifest/sid.h:

/* Auto-Generated file, DO NOT MODIFY! */
#define SERVICE_A_HANDLE ((psa_handle_t)((1 << 8)|(3 & 0xff)))

psa_service_a.c:

/* Rot Service API */
psa_status_t rot_service_a(void)
{
    return psa_call(SERVICE_A_HANDLE, PSA_IPC_CALL, NULL, 0, NULL, 0);
}
Proposal – Implementation ideas: Auto-connecting

- **Auto-connecting** during `psa_call()` - this can be handled inside SPM, without needing changes in the client or the SPRTL.

```c
spm_psa_call_handler(handle, type, call_params)
{
    if (IS_VALID_HANDLE(handle)) {
        msg = create_call_message(handle, call_params);
        if (IS_DEFAULT_HANDLE(handle) && NOT_CONNECTED(client, handle)) {
            validate_version(SID_LOOKUP(handle), VERSION(handle));
            msg.type = PSA_IPC_CONNECT;
            client->data = type; /* Backup the type for following call message. */
        }
        send_message(msg);
        wait_on(msg.event);
    }
    return;
}
```
Discussions – Related topics

• Memory usage – Should be tiny increase.
  • Per client dependencies storage – increased storage size.
  • Extra logic to dispatch ‘default_handle’ – code size in SPM.
  • Auto-connecting in SP Runtime – increases SP Runtime code size a bit.
  • But reduction in client code to connect and close transient handles, or to store handle variables.

• Performance – Almost the same.
  • A table lookup is needed for session-less services which cost several more lines.

• Will be a TF-M feature initially and working in parallel on an extension of PSA-FF-M specification to include this feature.
Thank You
Danke
Merci
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